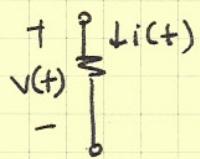


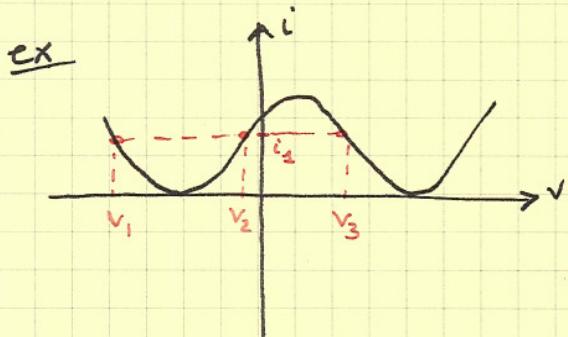
Non-linear resistors:



- Voltage controlled non-linear resistor

$$i(t) = f(v(t))$$

For each value of v , there is one and only one value of i (i.e. value of i is uniquely specified.)



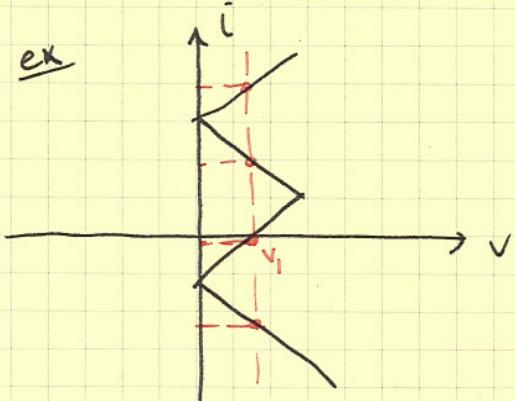
Draw lines perpendicular to v -axis.

You should encounter a single i value along each line. (e.g. pn-jnc diode, tunnel diode).

- Current controlled non-linear resistor

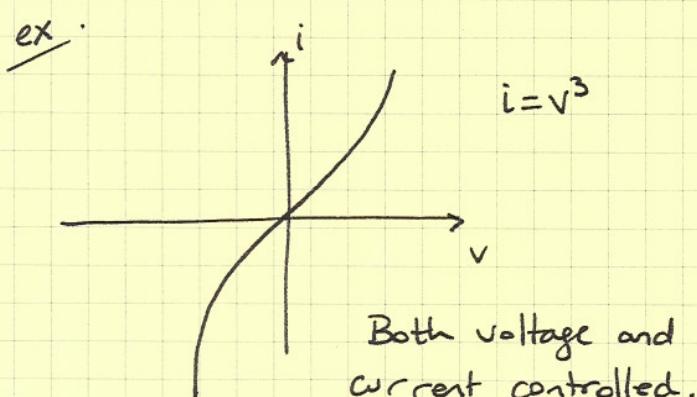
$$v(t) = g(i(t))$$

For each value of i , there is one and only one value of v . (e.g. glow tube)

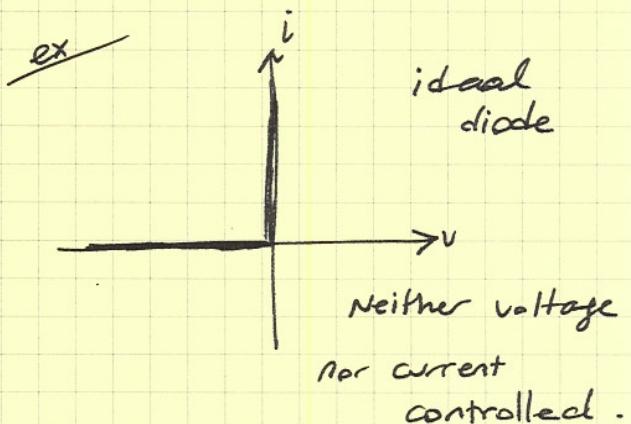


Draw lines perpendicular to i -axis.

You should encounter a single v -value along each line.



Both voltage and current controlled.



Neither voltage nor current controlled.

Non Linear Resistive Circuits:

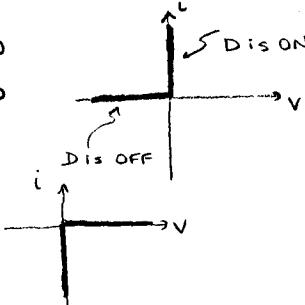
Diode: The diode is a two terminal, non-linear device that presents a relatively low resistance to current flow in one direction, and a relatively high resistance in the opposite direction.

Diode is NON-bilateral.

Ideal Diode: The ideal diode represents no resistance to current flow in the forward direction and an infinite resistance to current flow in the reverse direction.

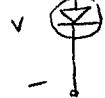
$$\text{OR: } i \uparrow + \quad \begin{array}{l} \text{D is ON: } V=0 \text{ if } i > 0 \\ \text{D is OFF: } i=0 \text{ if } V \leq 0 \end{array}$$

$$\text{OR: } i \uparrow + \quad \begin{array}{l} \text{D is ON: } V=0 \text{ if } i \leq 0 \\ \text{D is OFF: } i=0 \text{ if } V > 0 \end{array}$$



PN-junction Diode:

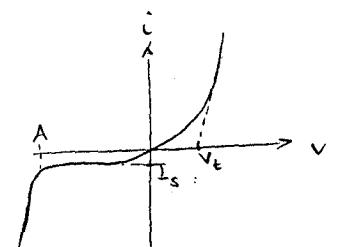
$$+ \quad i \quad i = I_s (e^{V/V_t} - 1)$$



I_s : Reverse saturation current (current in the diode when it is reverse biased with a large voltage)

V_t : Threshold voltage (forward voltage required to reach the region of upward swing)

* PN junction diode is a voltage controlled non-linear resistor.

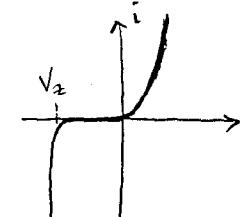
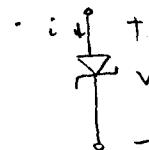


A: breakdown voltage (a few hundred volts)

Normal operating range: Right of point A.

(1)

Zener Diode:

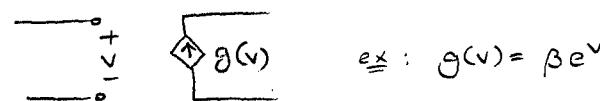


$$\text{OR: } i \uparrow + \quad \equiv \frac{1}{r_z} \approx \frac{1}{V_z}$$

(2)

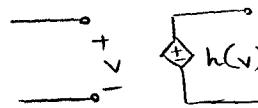
Non-linear Dependent Sources:

1) Voltage controlled current source (VCCS)

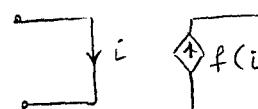


$$\text{ex: } g(v) = \beta e^v$$

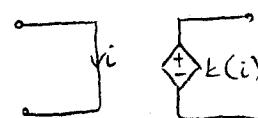
2) Voltage controlled voltage source (VCVS)



3) Current controlled current source (CCCS)



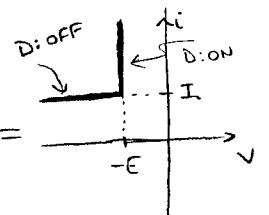
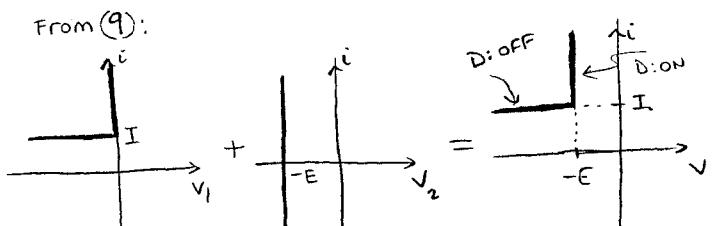
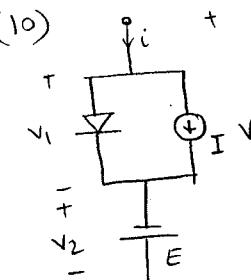
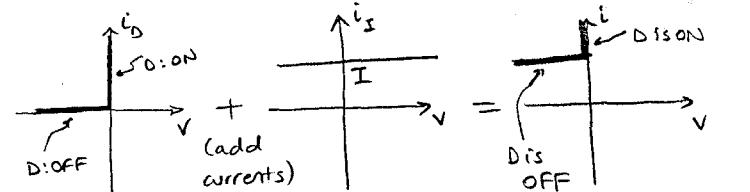
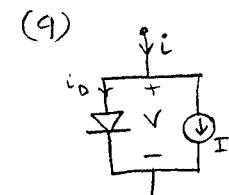
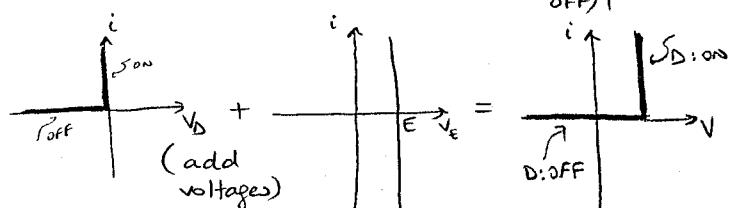
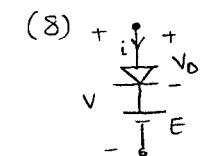
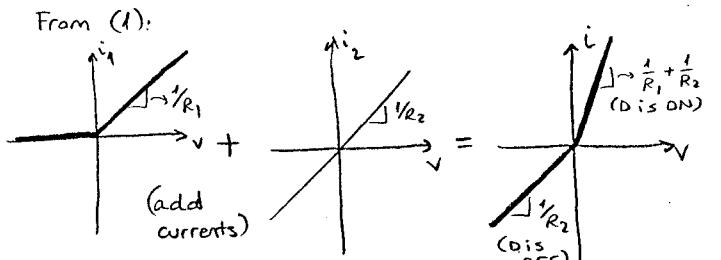
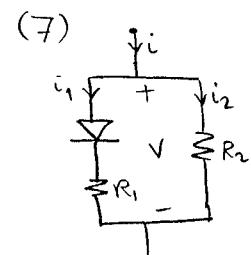
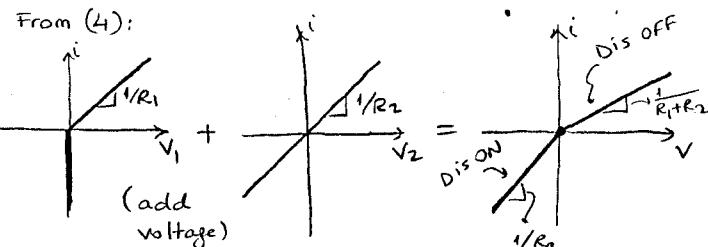
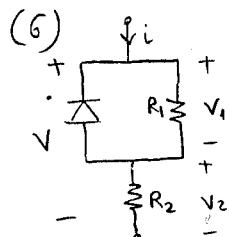
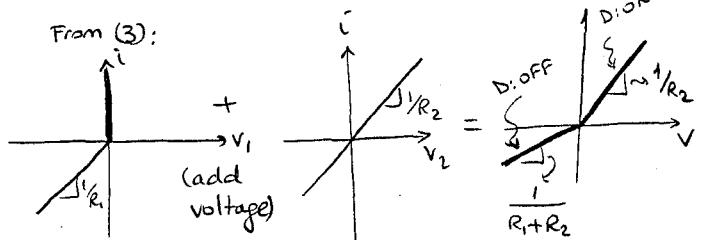
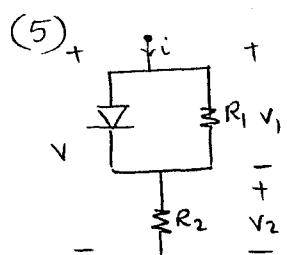
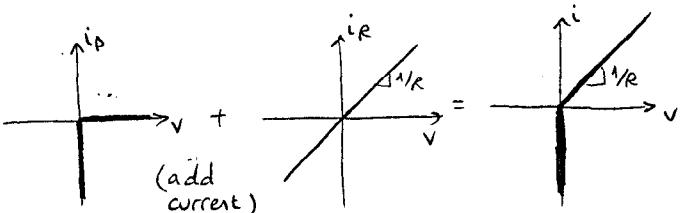
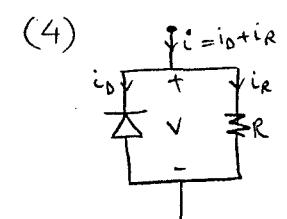
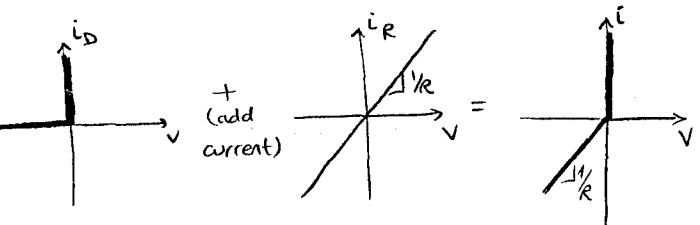
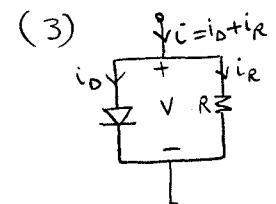
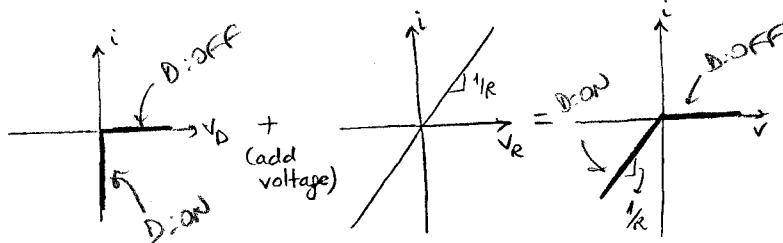
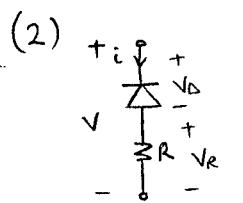
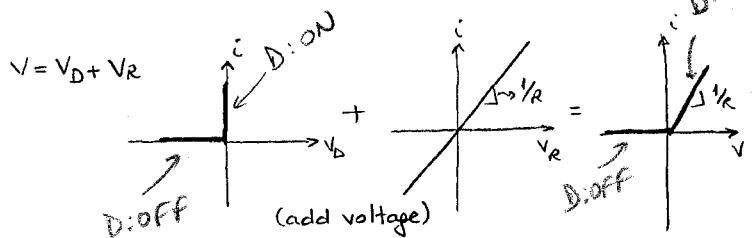
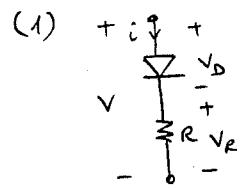
4) Current Controlled Voltage source (CCVS)

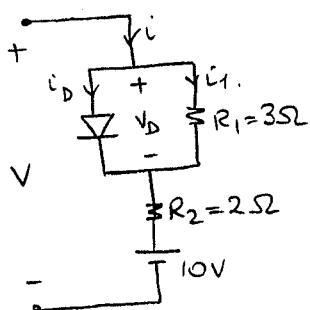


$$\text{ex: } k(i) = 3i^2$$

(3)

Series and Parallel Connections of Ideal Diodes, Resistors
and Constant Sources:



Example:Break Point:

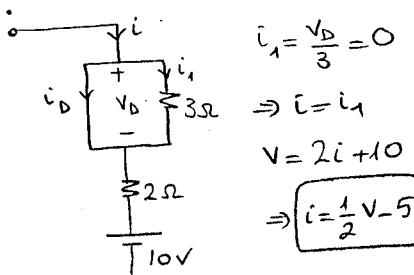
$$i_D = 0 \text{ and } V_D = 0$$

$$\text{then: } i_1 = 0 \text{ (since } V_D = V_{R_1} = 0\text{)} \\ i = 0$$

$$\Rightarrow V = V_D + i/R_2 + 10 = 10V$$

Assume D is ON:

$$\text{Then } V_D = 0, i_D > 0$$



For the diode to be ON:

$$i_D > 0 \Rightarrow i > 0$$

$$\Rightarrow \frac{1}{2}V - 5 > 0$$

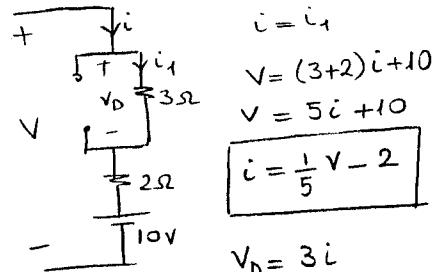
$$\Rightarrow V > 10$$

The i - v characteristics is then:

$$i = \begin{cases} \frac{1}{2}V - 5, & V > 10 \\ 0, & V = 10 \\ \frac{1}{5}V - 2, & V < 10 \end{cases}$$

Assume D is OFF:

$$\text{Then } i_D = 0, V_D < 0$$

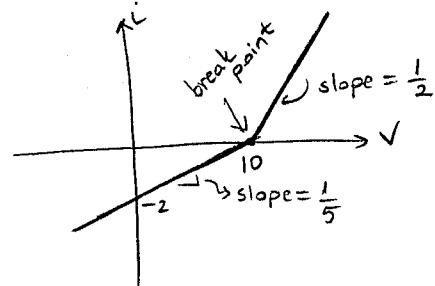
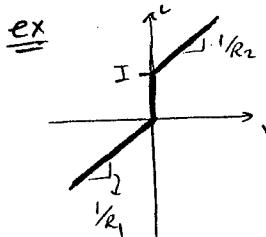
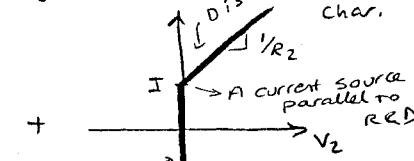
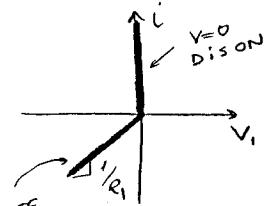


$$\Rightarrow V_D = 3 \cdot \left(\frac{1}{5}V - 2 \right)$$

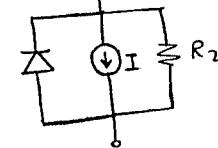
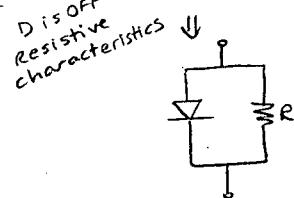
$$= \frac{3}{5}V - 6$$

For the diode to be OFF:

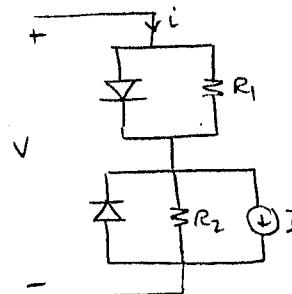
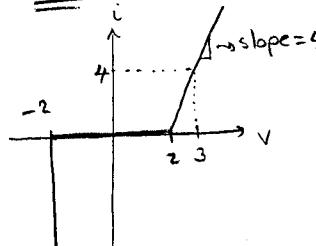
$$V_D < 0 \Rightarrow V < 10V$$

Synthesis (Use Ideal Diodes, Resistors and Constant Sources)we can obtain this i - v characteristics, by adding the voltages of:

(There are two break points)



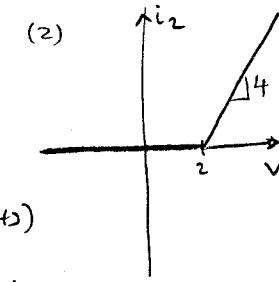
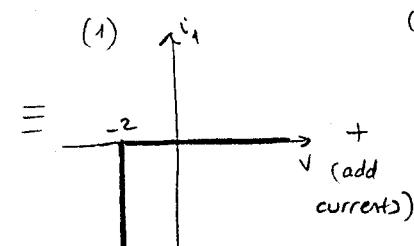
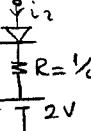
Then:

EX

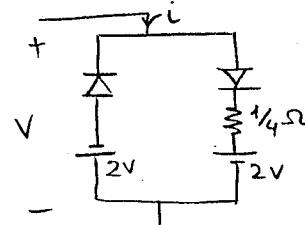
From (1):



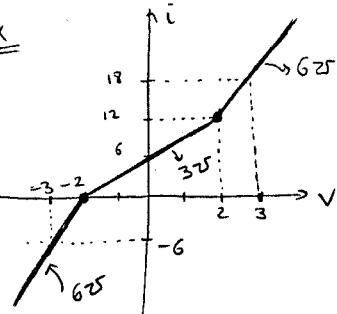
From (2):



⇒



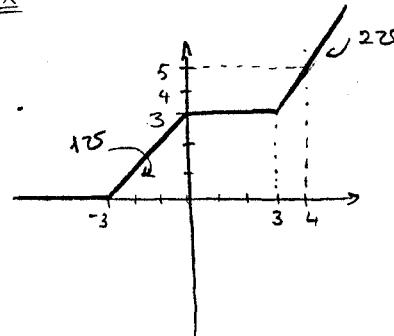
Ex



There are two breakpoints,
at -2 volts and at 2 Volts.

(A)

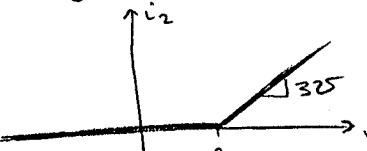
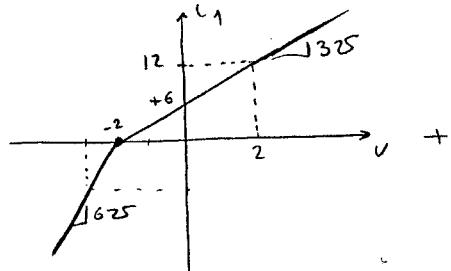
Ex



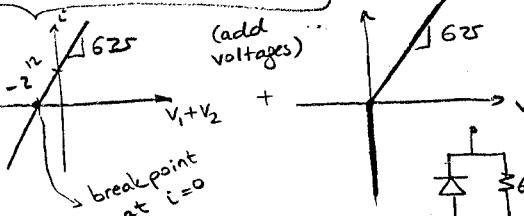
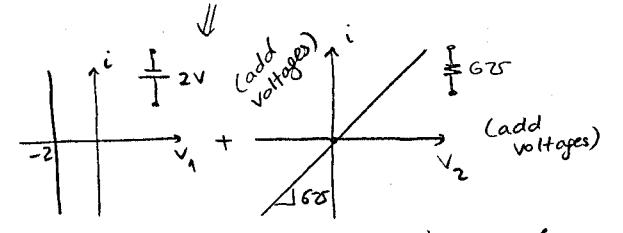
Design a circuit made up of
ideal diodes, passive resistors
and independent sources.

(Hint: there are 3 breakpoints,
so you should have 3 diodes
in your circuit)

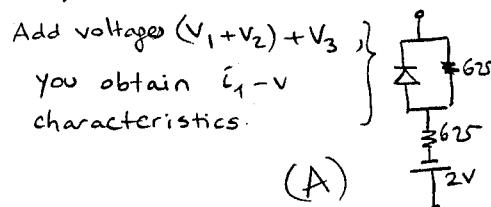
This characteristics can be obtained by adding currents of:



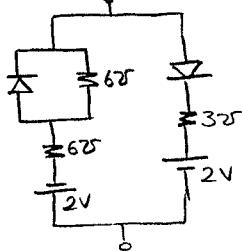
Add voltages



breakpoint
is at $i = 0$
therefore
slope should
change here



since we added
currents i_1 and i_2
at the beginning,
(A) and (B) are
connected in parallel:

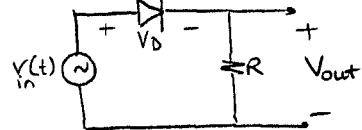


Diode Applications:

Rectifiers, filters, wave shaping circuits, etc.

Rectifier: The non-linear characteristics of a diode is used to convert alternating current into unidirectional, but pulsating current in the process called rectification.

Half wave rectifier:



$$1) 0 < t < \frac{\pi}{\omega}, v_{in}(t) > 0$$

Assume the diode is ON:

$$V_D = 0, i_D = i_R = \frac{V_{in}(t)}{R} > 0$$

since $i_D > 0$, our claim that D is ON is justified!

$$2) \frac{\pi}{\omega} < t < \frac{2\pi}{\omega}, v_{in}(t) < 0$$

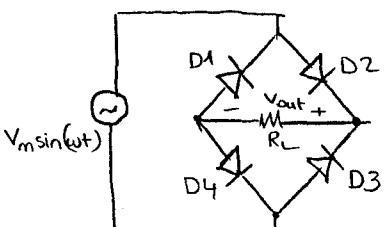
Assume the diode is OFF:

$$i_D = 0 = i_R \Rightarrow V_{out} = 0$$

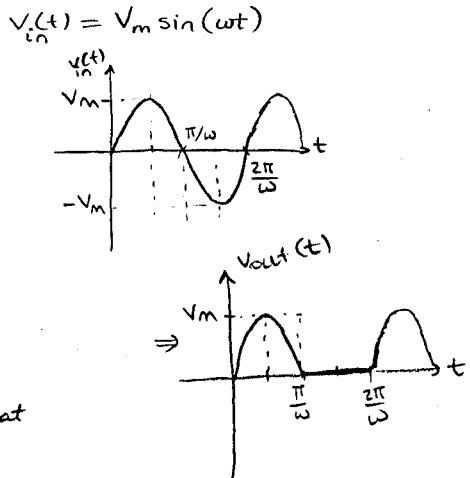
$$\Rightarrow V_D = V_{in} - V_{out} < 0$$

our claim that D is OFF is justified.

Exercise:



Find V_{out} and $V_{out,avg}$.



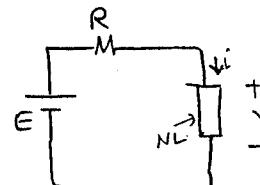
$$v_{in,avg} = \frac{1}{T} \int_0^T v_{in}(t) dt = 0$$

$$v_{out,avg} = \frac{1}{T} \int_0^{T/2} V_m \sin \omega t dt = \frac{V_m}{\pi}$$

↳ Average (DC) value of the half-wave rectified output voltage.

(7)

Circuits with a Single Non-linear Element:



(Typical biasing circuit)

Non-linear element has a characteristic:

$$I = g(V)$$

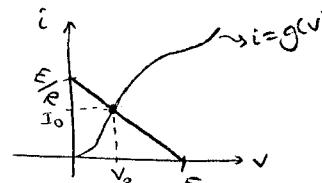
$$\text{From KVL: } E = Ri + V \Rightarrow E = Rg(V) + V$$

$$II) V = f(i)$$

$$\Rightarrow E = Ri + f(i)$$

$$\text{Let's study case I: } E = Rg(V) + V = Ri + V$$

Plot the $i-v$ characteristics for R and NL element:



$$\text{For NL element: } i = g(v)$$

$$\text{For R: } i = \frac{E-V}{R} = -\frac{V}{R} + \frac{E}{R}$$

this line is called the "Load line"

* The intersection point = operating point.

Q point: quiescent point.

Load line graphical method is used much in practice to determine operating points of non-linear circuits, because in practice, most of the non-linear circuit problems cannot be solved analytically, and v_i characteristics of a non-linear element is given as a measured curve.

Example: In the above non-linear circuit, $E=10V$, $R=100\Omega$

$$i = \begin{cases} 0.03V^2, & V \geq 0 \\ 0, & V < 0 \end{cases}$$

$$\text{Assume } V \geq 0: 10 = 100(0.03V^2) + V = 0 \Rightarrow 3V^2 + V - 10 = 0$$

$$E = Ri + V$$

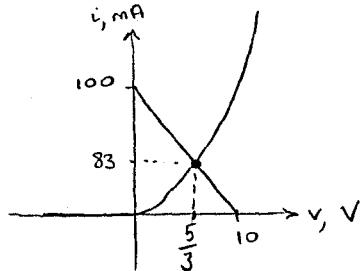
solving this equation, we find $V = -2V$

$$V = \frac{5}{3}V > 0$$

$$V_o = \frac{5}{3}V \Rightarrow I_o = 0.03 \times \frac{25}{9} \approx 0.083A$$

Solution:
at the operating point, (V_o)

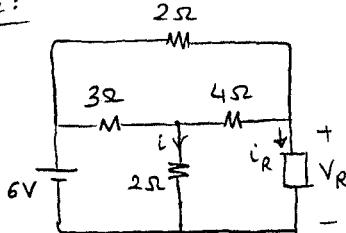
(8)



$$\frac{E}{R} = \frac{10}{100} = 0.1 \text{ A} \Rightarrow 100 \text{ mA}$$

(11)

Example:

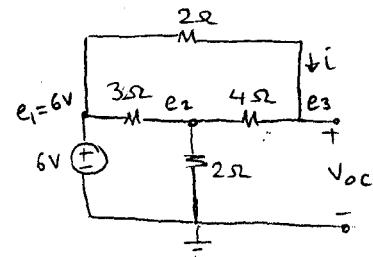


$$i_R = \begin{cases} 0.03V_R^2 & , V_R \geq 0 \\ 0 & , V_R < 0 \end{cases}$$

Find i .

Solution: Remove the nonlinear element and find the Thevenin equivalent of the rest of the circuit. Then connect R_L and solve for i_R and V_R . Finally, replace the non-linear element with either a voltage source of value V_R , or a current source of value i_R , and solve for i in this new circuit.

Step 1: Find the Thevenin equivalent circuit.



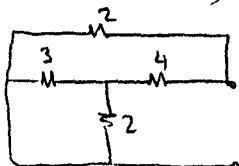
$$\frac{e_2 - 6}{3} + \frac{e_2}{2} + \frac{e_2 - 6}{4+2} = 0$$

$$6e_2 = 18 \Rightarrow e_2 = 3 \text{ V}$$

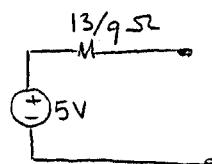
$$i = \frac{6 - e_2}{6} = \frac{1}{2} \text{ A.}$$

$$V_{oc} = V_{th} = e_3 = 6 - 2 \cdot i = \underline{\underline{5 \text{ V}}}$$

$R_{th} = ?$ (kill 6V)

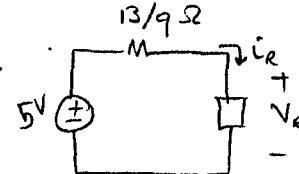


$$R_{th} = 2 // [4 + (2 // 3)] = \frac{13}{9} \Omega$$



= Thevenin Eq.

Step 2: Connect the non-linear load, and find i_R , V_R : (12)



$$V \geq 0 : i_R = 0.03V_R^2$$

$$5 = \frac{13}{9} \cdot (0.03V_R^2) + V_R$$

$$V_R = 4.22 \text{ V}$$

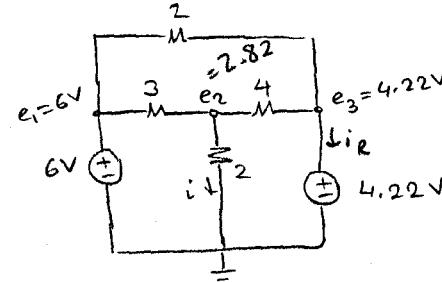
$$V_R = -27.29 \text{ V}$$

$$\checkmark V_R > 0$$

$$\times V_R < 0$$

$$V_R = 4.22 \text{ V}, i_R = 0.03 \cdot (4.22)^2 = 0.53 \text{ A}$$

Step 3: Replace the n.l. load with a voltage (or current) source:



$$\frac{e_2 - 6}{3} + \frac{e_2 - 4.22}{4} + \frac{e_2}{2} = 0$$

$$\rightarrow e_2 = 2.82 \text{ V}$$

$$i = \frac{e_2}{2} = 1.41 \text{ A}$$

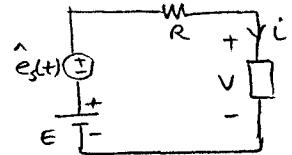
Exercise: Find i by replacing the load with a current source of value $i_R = 0.53 \text{ A}$.

$$i_R + \frac{4.22 - 2.82}{4} + \frac{4.22 - 6}{2} = 0 \Rightarrow i_R = 0.54 \text{ A!}$$

(13)

Small Signal Analysis:

A circuit with a DC source and a time-varying input (e.g. a sinusoidal waveform) can be analyzed by using small signal analysis method, if the magnitude of input (or sinusoidal signal) is sufficiently small.



$$e_s = E + \hat{e}_s \quad \text{where } |\hat{e}_s| \ll E$$

$$i = g(v)$$

$$\text{let } \hat{e}_s(t) = V_m \cos \omega t.$$

$$\text{Then, } -V_m \leq \hat{e}_s(t) \leq V_m$$

$$\text{and } E - V_m \leq e_s \leq E + V_m$$

* The actual current and voltage vary as a function of time in the neighborhood of the operating point, Q.

$$e_s = R i + v = R g(v) + v$$

$$\text{If } \hat{e}_s = 0 \Rightarrow e_s = E \quad \text{and} \quad E = R g(V_o) + V_o, \quad I_o = g(V_o)$$

$$v = V_o + \hat{v}(t)$$

Expand current in Taylor series about V_o :

$$i = g(v) = g(V_o + \hat{v}) = g(V_o) + \underbrace{\frac{dg}{dv} \Big|_{v=V_o} \hat{v}}_{I_o} + \underbrace{\frac{1}{2!} \frac{d^2g}{dv^2} \Big|_{v=V_o} \hat{v}^2}_{\hat{i}} + \dots$$

$$e_s = E + \hat{e}_s = R(I_o + \hat{i}) + V_o + \hat{v}$$

$$\hat{i} = \left. \frac{dg}{dv} \right|_{v=V_o} \hat{v} + \text{higher order terms}$$

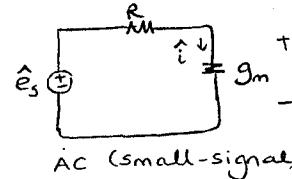
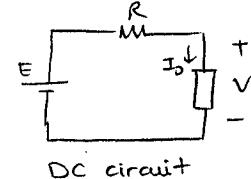
negligible

define: $g_m \triangleq \left. \frac{dg}{dv} \right|_{v=V_o}$ → Note that this is the slope of the characteristic of the nonlinear element at the operating point.

$$\hat{i} \approx g_m \hat{v}$$

(14)

Now that we used a linear approximation of the non-linear element, we can use superposition.



Example: In the above circuit:

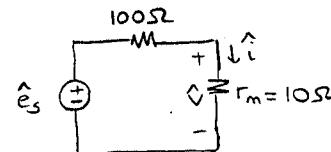
$$E = 10V, \quad R = 100\Omega, \quad \hat{e}_s = \sin(100t)$$

$$i = \begin{cases} 0.03v^2, & v \geq 0 \\ 0, & v < 0 \end{cases}$$

Previously, the DC circuit was solved: $I_o = \frac{250}{3} \text{ mA}, V_o = \frac{5}{3} \text{ V}$

Now, let's solve the AC part:

$$g_m = \left. \frac{di}{dv} \right|_{v=V_o} = \left. \frac{d[0.03v^2]}{dv} \right|_{v=\frac{5}{3}} = 0.03 \times 2V_o = 0.125 = 100 \text{ mS} \Rightarrow r_m = 10\Omega$$



$$\hat{v} = \frac{10}{110} \rightarrow \hat{e}_s = \frac{1}{11} \sin(100t) \text{ (V)}$$

$$\hat{i} = \frac{\hat{v}}{10} = 9.09 \sin(100t) \text{ (mA)}$$

$$\Rightarrow v = V_o + \hat{v} = \frac{5}{3} + 0.0909 \sin(100t) \text{ Volts} \rightarrow \begin{aligned} V_{\max} &= 1.757 \text{ V} \\ V_{\min} &= 1.575 \text{ V.} \end{aligned}$$

$$i = I_o + \hat{i} = \frac{250}{3} + 9.09 \sin(100t) \text{ (mA)} \rightarrow \begin{aligned} I_{\max} &= 92.42 \text{ mA} \\ I_{\min} &= 74.24 \text{ mA.} \end{aligned}$$

To make a comparison, evaluate v when $e_{s,\max} = 11 \text{ V}$ and $e_{s,\min} = 9 \text{ V}$.

$$e_{s,\max} = 11V = \frac{R}{100 + 0.03v^2} + V \quad e_{s,\min} = 9V = \frac{R}{100 + 0.03v^2} + V$$

$$v^2 + \frac{V}{3} - \frac{11}{3} = 0$$

$$\Rightarrow v = 1.755 \text{ V} \rightarrow V_{\max}$$

$$i = 92.445 \text{ mA} \rightarrow I_{\max}$$

$$v^2 + \frac{V}{3} - \frac{9}{3} = 0$$

$$\Rightarrow v = 1.573 \text{ V} \rightarrow V_{\min}$$

$$i = 74.266 \text{ mA} \rightarrow I_{\min}$$